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fullsvd() — Full singular value decomposition

Description Syntax Remarks and examples Conformability

Diagnostics Also see

Description

fullsvd(A, U, s, Vt) calculates the singular value decomposition of $m \times n$ matrix A, returning the result in U, s, and Vt. Singular values in s are sorted from largest to smallest.

fullsdiag(s, k) converts column vector s returned by fullsvd() into matrix S. In all cases, the appropriate call for this function is

```
S = \text{fullsdiag}(s, \text{rows}(A) - \text{cols}(A))
```

 $_{\text{fullsvd}}(A, U, s, Vt)$ does the same as fullsvd(), except that, in the process, it destroys A. Use of $_{\text{fullsvd}}()$ in place of fullsvd() conserves memory.

_svd_la() is the interface to the LAPACK SVD routines and is used in the implementation of the previous functions. There is no reason you should want to use it. _svd_la() is similar to _fullsvd(). It differs in that it returns a real scalar equal to 1 if the numerical routines fail to converge, and it returns 0 otherwise. The previous SVD routines set s to contain missing values in this unlikely case.

Syntax

void fullsvd(numeric matrix A, U, s, Vt)

numeric matrix fullsdiag(numeric colvector s, real scalar k)

void _fullsvd(numeric matrix A, U, s, Vt)

real scalar $_svd_la(numeric\ matrix\ A\ ,\ U\ ,\ s\ ,\ Vt)$

Remarks and examples

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Remarks are presented under the following headings:

Introduction
Relationship between the full and thin SVDs
The contents of s
Possibility of convergence problems

Documented here is the full SVD, appropriate in all cases, but of interest mainly when $A: m \times n$, m < n. There is a thin SVD that conserves memory when $m \ge n$; see [M-5] $\operatorname{svd}()$. The relationship between the two is discussed in *Relationship between the full and thin SVDs* below.

Introduction

The SVD is used to compute accurate solutions to linear systems and least-squares problems, to compute the 2-norm, and to determine the numerical rank of a matrix.

The singular value decomposition (SVD) of A: $m \times n$ is given by

$$A = USV'$$

where

U: $m \times m$ and orthogonal (unitary)

S: $m \times n$ and diagonal

V: $n \times n$ and orthogonal (unitary)

When A is complex, the transpose operator ' is understood to mean the conjugate transpose operator.

Diagonal matrix S contains the singular values and those singular values are real even when A is complex. It is usual (but not required) that S is arranged so that the largest singular value appears first, then the next largest, and so on. The SVD routines documented here do this.

The full SVD routines return U and Vt = V'. S is returned as a column vector s, and S can be obtained by

$$S = \text{fullsdiag}(s, \text{rows}(A) - \text{cols}(A))$$

so we will write the SVD as

$$A = U * \text{fullsdiag}(s, \text{rows}(A) - \text{cols}(A)) * Vt$$

Function fullsvd(A, U, s, Vt) returns the U, s, and Vt corresponding to A.

Relationship between the full and thin SVDs

A popular variant of the SVD is known as the thin SVD and is suitable for use when $m \ge n$. Both SVDs have the same formula,

$$A = USV'$$

but U and S have reduced dimensions in the thin version:

Matrix	Full SVD	Thin SVD
\overline{U} :	$m \times m$	$m \times n$
<i>S</i> :	$m \times n$	$n \times n$
V:	$n \times n$	$n \times n$

When m = n, the two variants are identical.

The thin SVD is of use when m > n, because then only the first n diagonal elements of S are nonzero, and therefore only the first n columns of U are relevant in A = USV'. There are considerable memory savings to be had in calculating the thin SVD when $m \gg n$.

As a result, many people call the thin SVD the SVD and ignore the full SVD altogether. If the matrices you deal with have $m \ge n$, you will want to do the same. To obtain the thin SVD, see [M-5] $\mathbf{svd}()$.

Regardless of the dimension of your matrix, you may wish to obtain only the singular values. In this case, see svdsv() documented in [M-5] svd(). That function is appropriate in all cases.

The contents of s

Given A: $m \times n$, the singular values are returned in s: $\min(m, n) \times 1$.

Let's consider the m=n case first. A is $m\times m$ and the m singular values are returned in s, an $m\times m$ 1 column vector. If A were 3×3 , perhaps we would get back

If we needed it, we could obtain S from s simply by creating a diagonal matrix from s

although the official way we are supposed to do this is

:
$$S = \text{fullsdiag}(s, \text{rows}(A) - \text{cols}(A))$$

and that will return the same result.

Now let's consider m < n. Let's pretend that A is 3×4 . The singular values will be returned in 3 \times 1 vector s. For instance, s might still contain

The S matrix here needs to be 3×4 , and fullsdiag() will form it:

The final case is m > n. We will pretend that A is 4×3 . The s vector we get back will look the same

but this time, we need a 4×3 rather than a 3×4 matrix formed from it.

Possibility of convergence problems

See Possibility of convergence problems in [M-5] svd(); what is said there applies equally here.

Conformability

```
fullsvd(A, U, s, Vt):
     input:
                     A:
                              m \times n
     output:
                     U:
                              m \times m
                              \min(m, n) \times 1
                      s:
                    Vt:
                              n \times n
                              void
                result:
fullsdiag(s, k):
     input:
                              r \times 1
                      s:
                     k:
                              1 \times 1
     output:
                              r + k \times r, if k \ge 0
                result:
                              r \times r - k, otherwise
\_fullsvd(A, U, s, Vt):
     input:
                     A:
                              m \times n
     output:
                              0 \times 0
                     A:
                     U:
                              m \times m
                              \min(m,n) \times 1
                      s:
                    Vt:
                              n \times n
```

result:

void

```
_{\text{svd\_la}(A, U, s, Vt)}:
     input:
                       A:
                                m \times n
     output:
                       A:
                                m \times n,
                                            but contents changed
                      U:
                                m \times m
                       s:
                                \min(m,n)\times 1
                      Vt:
                                n \times n
                                 1 \times 1
                  result:
```

Diagnostics

fullsvd(A, U, s, Vt) and $_$ fullsvd(A, s, Vt) return missing results if A contains missing. In all other cases, the routines should work, but there is the unlikely possibility of convergence problems, in which case missing results will also be returned; see Possibility of convergence problems in [M-5] **svd()**.

_fullsvd() aborts with error if A is a view.

Direct use of _svd_la() is not recommended.

Also see

```
[M-5] norm() — Matrix and vector norms
[M-5] pinv() — Moore–Penrose pseudoinverse
[M-5] rank() — Rank of matrix
[M-5] svd() — Singular value decomposition
[M-5] sysolve() — Solve AX=B for X using singular value decomposition
[M-4] Matrix — Matrix functions
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